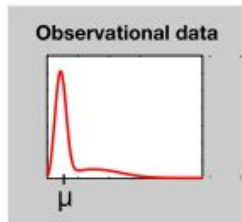


Intro to ABC

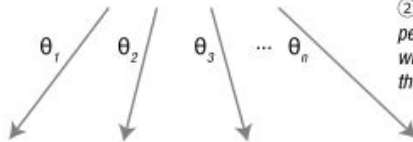


Prior distribution of model parameter θ

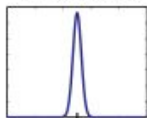


① Compute summary statistic μ from observational data

② Given a certain model, perform n simulations, each with a parameter drawn from the prior distribution

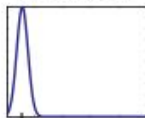


Simulation 1



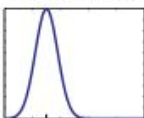
μ_1

Simulation 2



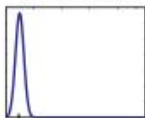
μ_2

Simulation 3



μ_3

Simulation n



μ_n

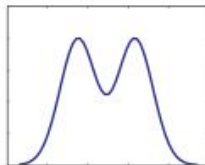
③ Compute summary statistic μ_i for each simulation

$$\rho(\mu_i, \mu) \stackrel{?}{\leq} \epsilon$$



④ Based on a distance $\rho(\cdot, \cdot)$ and a tolerance ϵ , decide for each simulation whether its summary statistic is sufficiently close to that of the observed data.

Posterior distribution of model parameter θ



⑤ Approximate the posterior distribution of θ from the distribution of parameter values θ_i associated with accepted simulations.

Likelihood-Free Rejection Sampling Algorithm

Inputs:

- A target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure for generating data under the model $p(y_{obs}|\theta)$.
- A proposal density $g(\theta)$, with $g(\theta) > 0$ if $\pi(\theta|y_{obs}) > 0$.
- An integer $N > 0$.

Sampling:

For $i = 1, \dots, N$:

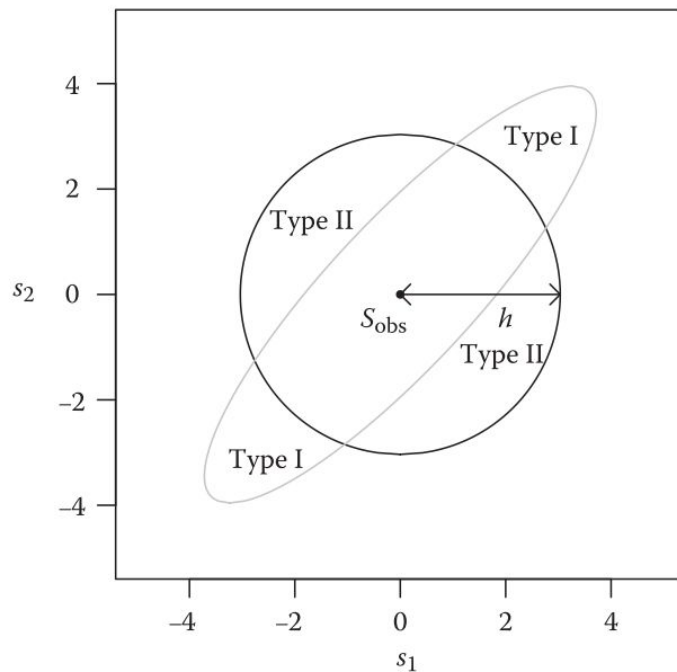
1. Generate $\theta^{(i)} \sim g(\theta)$ from sampling density g .
2. Generate $y \sim p(y|\theta^{(i)})$ from the likelihood.
3. If $y = y_{obs}$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$,
where $K \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$. Else go to 1.

Output:

A set of parameter vectors $\theta^{(1)}, \dots, \theta^{(N)}$ which are samples from $\pi(\theta|y_{obs})$.

Likelihood-Free Rejection Sampling Algorithm

3. If $\|y - y_{obs}\| \leq h$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$,
where $K \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$.



Kernel functions instead of indicators

rejecting θ if $\|y - y_{obs}\| \leq h$

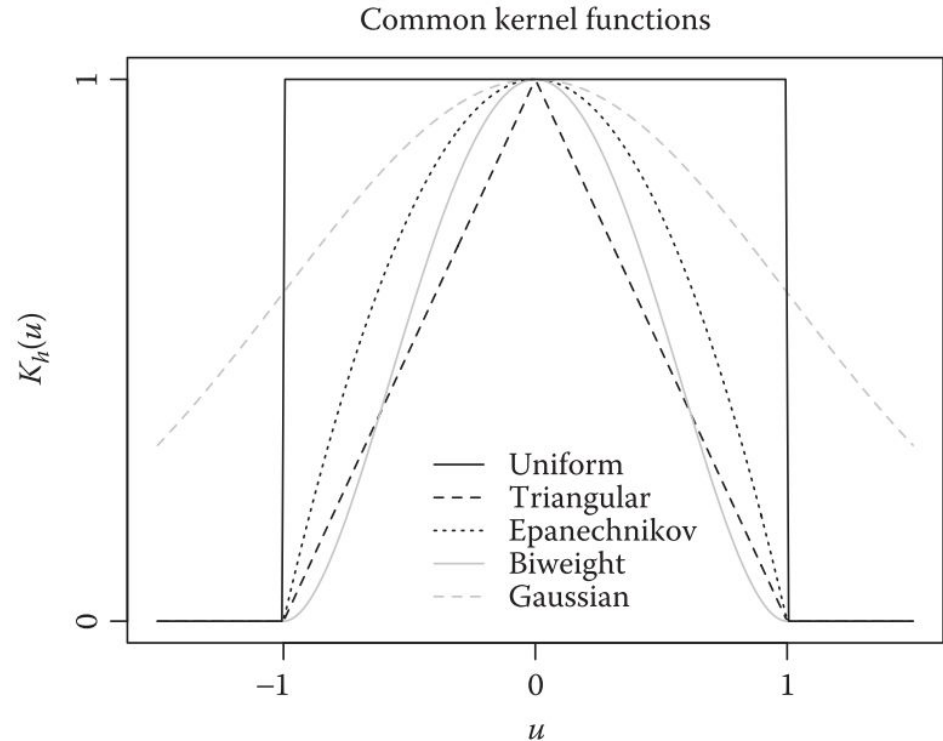


$$I(\|y - y_{obs}\| \leq h)p(y|\theta)g(\theta)$$

As an alternative, use a kernel function:

$$K_h(u) = \frac{1}{h} K\left(\frac{u}{h}\right)$$


$$u = \|y - y_{obs}\|$$




Curse of dimensionality - Summary statistics

Sampling:

For $i = 1, \dots, N$:

1. Generate $\theta^{(i)} \sim g(\theta)$ from sampling density g .
2. Generate $y \sim p(y|\theta^{(i)})$ from the likelihood.
3. Compute summary statistic $s = S(y)$. 
4. Accept $\theta^{(i)}$ with probability $\frac{K_h(\|s - s_{obs}\|)\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$
where $K \geq K_h(0) \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$. Else go to 1.

Output:

A set of parameter vectors $\theta^{(1)}, \dots, \theta^{(N)} \sim \pi_{ABC}(\theta|s_{obs})$. 

Summary questions:

- Choice of h and distance measure
- Choice of kernel
- Summary statistics
- Approximations due to other ABC techniques
- Sensitivity to prior
- Applications