

## The setting

- Nonlinear dynamical system:  $u(t) = \Phi_t(u(0); \theta)$ .
- Ecological model (Ricker map) as motivation:  $N_t = rN_{t-1}e^{-N_{t-1}+e_{t-1}}$ ,  
 $e_t \sim \mathcal{N}(0, \sigma_e^2)$ ,
- Data observed  $y_t \sim \text{Pois}(\phi N_t)$  so  $\theta = (r, \sigma_e^2, \phi)$ . Call the full dataset  $y$  from here on in.
- Likelihood is numerically horrific. How to infer  $\theta$  given data  $y$ ?

## The basic idea

- Log-likelihood poorly behaved — how to smooth the log-likelihood surface?
- Know from central limit theorem: if  $\{x_1, x_2, \dots, x_n\}$ ,  $\mathbb{E}[x_i] = \mu$ ,  $\text{Var}[x_i] = \sigma^2$ , are draws from some probability distribution then  $\sqrt{n}(\bar{x}_n - \mu) \rightarrow \mathcal{N}(0, \sigma^2)$ .  
Generalizes to multivariate setting as you would expect.
- Now reduce  $y$  to  $s$ , a vector of summary statistics, and assume  $s \sim \mathcal{N}(\mu_\theta, \Sigma_\theta)$ .
- Given a value of  $\theta$  we then generate a set of replicate datasets  $\{y_1^*, y_2^*, \dots\}$  and corresponding summary statistics  $\{s_1^*, s_2^*, \dots\}$ . Then we use these to compute the log likelihood (to a constant)

$$l_s(\theta) = -\frac{1}{2} (s - \hat{\mu}_\theta) \hat{\Sigma}_\theta^{-1} (s - \hat{\mu}_\theta)^\top,$$

where  $\hat{\mu}_\theta$  and  $\hat{\Sigma}_\theta$  are each estimated from the replicates  $s_i^*$ . This is a proxy for assessing the likelihood of  $\theta$  through the summary statistics.

## Inference for $\theta$

Use MCMC. Given a starting point  $\theta^{[0]}$  we proceed for each  $k$

- 1 Generate  $\theta^* \sim q(\theta^{[k-1]})$ .
- 2 Compute  $\alpha = \exp(l_s(\theta^*) - l_s(\theta^{[k-1]}))$
- 3 Set  $\theta^{[k]} = \theta^*$  w.p.  $\alpha$ , otherwise  $\theta^{[k]} = \theta^{[k-1]}$ .

Samples drawn from  $l_s$

## Case study

- Adult blowfly populations are given from the delay differential equation:

$$\frac{dN}{dt} = PN(t - \tau)e^{N(t-\tau)/N_0} - \delta N(t).$$

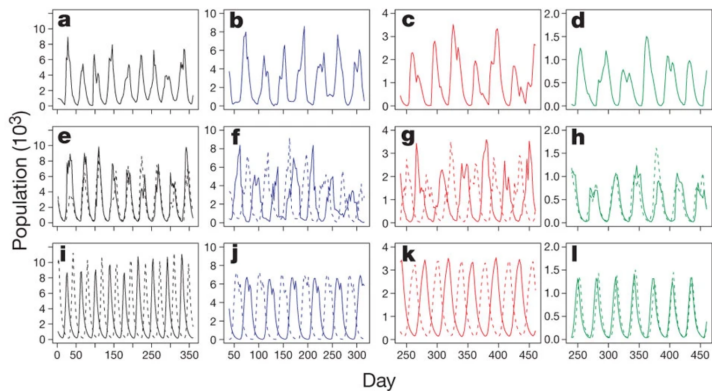
Discretized to give

$$N_{t+1} = R_t + S_t,$$

where  $R_t \sim \text{Pois}(PN_{t-\tau} \exp(-N_{t-\tau}/N_0)e_t)$ , and  $S_t \sim \text{Binom}(\exp(-\delta\varepsilon_t), N_t)$ .  
Stochastic terms  $e_t, \varepsilon_t$  are Gamma random variables with unit means and variances  $\sigma_p^2$  and  $\sigma_d^2$ .

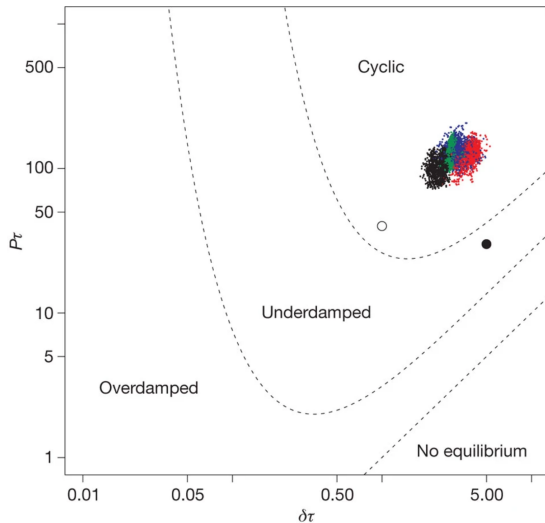
- I have no idea how these come about.
- Parameters thus  $\theta = (P, N_0, \delta, \tau, \sigma_p, \sigma_d)$ .

# Results



**a, b**, Two laboratory adult populations of sheep blowfly maintained under adult food limitation<sup>4,5</sup>. **c, d**, As in **a** and **b** but maintained under moderate and more severe juvenile food limitation<sup>4</sup>. **e-h**, Two replicates (one solid, one dashed) from the full model (equation (4)) fitted separately to the data shown in each of panels **a-d**, immediately above. **i-l**, As in **e-h** for the model with demographic stochasticity only. The observations are made every second day. The simulation phase is arbitrary. Notice the qualitatively good match of the dynamics (**e-h**) of the full model (equation (4)) to the data, relative to the insufficiently variable dynamics of the model with demographic stochasticity only (**i-l**).

# Results



The coloured points are samples from the stability-controlling parameter combinations  $\delta\tau$  and  $Pr$ , plotted (with matching colour coding) for each experimental run shown in Fig. 3. The open and filled circles show stability properties for alternative chain starting conditions: they give indistinguishable results, although the conditions marked by the filled circle lie in the plausible range for external noise-driven dynamics<sup>14</sup>. The dynamics comprise limit cycles perturbed by noise but not driven by noise. The fluctuations are driven by the intrinsic population-dynamic processes, not by random variation exciting a resonance in otherwise stable dynamics.

## Discussion

- Why no Bayes? Would make sense to incorporate prior knowledge in the model.
- How to choose summary statistics? This is given lengthy discussion in the SI.
- What do parameter estimates/sampling results look like? This is shown in the SI but would be nice to see?